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What is claimed is:

1. A navigation system for a position self control robot including a main body having a locomotion unit, the navigation system comprising:

two-dimensional (2D) barcodes formed at predetermined intervals on a floor having a predetermined size, the 2D barcodes respectively having different unique coordinate values;

a barcode reader installed at a predetermined position in a lower portion of the main body to read a 2D barcode on the floor; and

a control unit installed at the main body to be electrically connected with the barcode reader, the control unit recognizing absolute coordinates within a predetermined area, which are stored in memory, based on a unique coordinate value of the 2D barcode read by the barcode reader, applying the absolute coordinates to a programmed locomotion algorithm, and controlling the locomotion unit to move the main body.

- 2. The navigation system of claim 1, further comprising a light emitting device installed near the barcode reader to emit light having a predetermined wavelength range to the floor.
- 3. The navigation system of claim 2, wherein the light emitting device emits light having a wavelength range between 300 nm and 850 nm.

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4. A floor material for providing absolute coordinate information to enable a position self control robot to recognize absolute coordinates in a move space, the floor material comprising at least one first sheet made by reversely printing a plurality of two-dimensional (2D) barcodes respectively having different unique coordinate values at predetermined intervals on a rear side of a transparent material having a

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predetermined area and by forming an adhesive layer on the rear side of the transparent material so that the 2D barcodes are normally seen from a surface of the floor material.

5. The floor material of claim 4, wherein the 2D barcodes are printed using one of visible color ink and invisible secret ink.

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- 6. The floor material of claim 4, wherein the 2D barcodes are arranged at equal intervals in a matrix pattern.
- 7. The floor material of claim 4, wherein the 2D barcodes are arranged at equal intervals along a plurality of concentric circles.
- 8. A floor material for providing absolute coordinate information to enable a position self control robot to recognize absolute coordinates in a move space, the floor material comprising a plurality of second sheets each made by reversely printing a single two-dimensional (2D) barcode having a unique coordinate value on a rear side of a transparent material having a predetermined area and by forming an adhesive layer on the rear side of the transparent material so that the 2D barcode is normally seen from a surface of the floor material.
- 9. The floor material of claim 8, wherein the 2D barcode is printed using one of visible color ink and invisible secret ink.
- 10. The floor material of claim 9, wherein the second sheets are arranged at equal intervals in a matrix pattern.
- 11. The floor material of claim 9, wherein the second sheets are arranged at equal intervals along a plurality of concentric circles.

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- 12. A floor material for providing absolute coordinate information to enable a position self control robot to recognize absolute coordinates in a move space, the floor material comprising a plurality of two-dimensional (2D) barcodes printed on a surface thereof at predetermined intervals, the 2D barcodes respectively having different unique coordinate values.
- 13. The floor material of claim 12, wherein the 2D barcodes are printed using one of visible color ink and invisible secret ink.
- 14. The floor material of claim 12, wherein the 2D barcodes are arranged at equal intervals in a matrix pattern.
- 15. The floor material of claim 12, wherein the 2D barcodes are arranged at equal intervals along a plurality of concentric circles.
 - 16. The floor material of claim 12, further comprising a coating sheet that is made of a transparent material and is bonded to the surface on which the 2D barcodes are printed.

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